

RollerDrive® RTB series

Tilting rotary table for small MCs



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The RTB series is a compact, lightweight, tilted rotary table built to respond to the increasing number of machining variations with small MCs, the increasing complexity and size of workpieces. Even for workpieces that require multiple processes, use of the RTB series, equipped with A and C axes, enables process consolidation, efficient machining postures and optimized tool selection.

In addition, in order to meet the needs of unmanned machines and the introduction of robots, we have developed a rotary joint with up to 6 ports that can be used for automatic workpiece loading/unloading and seating confirmation. Further, the use of the RollerDrive mechanism eliminates the need for clamping during machining, so the indexing time can be reduced by approximately one-third, compared with the conventional worm gear mechanism on rotary tables with a clamping operation. Since continuous operation only needs a lubrication oil change from time to time, the RTB RollerDrive eliminates the need for periodic recalibration, unlike a conventional worm gear rotary table. This contributes to an extended operating time for equipment. The RTB is ideal for small MCs, by providing improvements in automation and productivity.



- **Features**
- ■No-backlash RollerDrive mechanism
- OClampless processing drastically increases the ratio of cutting to non-cutting time
- OLightweight and compact, and can be mounted on the #30 vertical MCs
- Rotary joint up to 6 ports
- •Routine maintenance is just an oil change, nothing else.

CNC ROTARY TABLE

RSR series



High productivity circular table with an installed rotary joint 12+1p model for compact MCs

RCD series



Standard model with improved performance thanks to a re-engineered design

RTD series



A two-axis tilting rotary table securely held at both ends achieves both a thin, compact body that is highly rigid

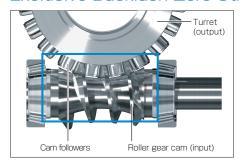
RTA series

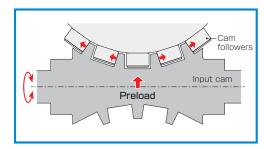


Large, high-power tilting rotary table with a dual-axis tilting drive.

No Maintenance and Excellent Price Performance

Exclusive Backlash Zero Structure





Multiple roller followers, come into contact from both sides (in pairs) without gaps to provide efficient rolling transmission without backlash.

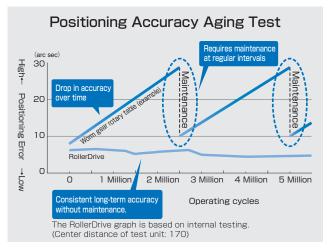
Features

Rolling contact

Preload

- No backlash (play).
- Preloadable for high rigidity.
- Clampless processing reduces positioning time.
- OHigh accuracy and good efficiency.
 OAccuracy does not deteriorate over time and maintains initial accuracy for a long period of time.

Consistent long-term accuracy without maintenance.



Worm gear models

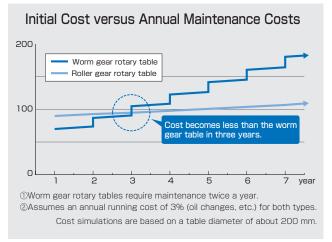
Accuracy declines over time. Requires maintenance to achieve initial accuracy.

■ RollerDrive

Accuracy is consistent with no maintenance even after 5 million operation cycles.

Cost Comparison with a Worm Gear Rotary Table

Offers Long-term Use without Maintenance



■ Worm gear models

Maintenance costs occur once or twice a year to adjust the backlash.

■ RollerDrive

Long-term use is possible without any mechanical maintenance. Beats the cost of a worm gear even after adding annual running costs to the initial investment cost. Price performance continues thereafter.

Based on internal calculations.

Extended Accuracy

Compared against a worm gear for over 5 million indexes.

■ Test conditions

• Table size: Output table diameter: 170 mm

• Index period: 36° (unidirectional)

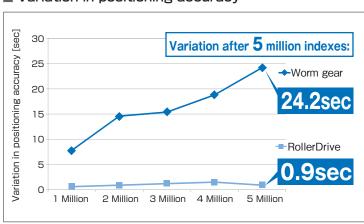
• Indexing time: 0.35sec

Results after 5 million indexes:

Item	Worm gear	RollerDrive
Variation in positioning accuracy	24.2sec	0.9sec
Backlash (measured at R60)	18μm (15μm→33μm)	_

Based on internal testing data

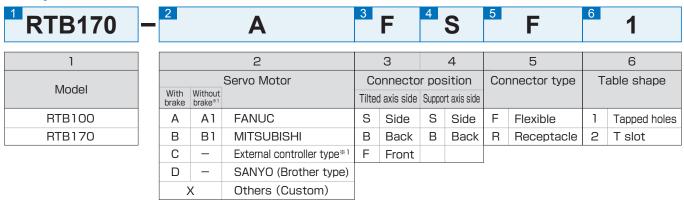
Variation in positioning accuracy



2

Product code

Rotary table



01

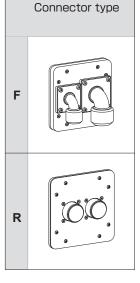
	7			
	Option			
Rotary joint				
J	Number of ports			
	RTB1706P			
Blank	None			

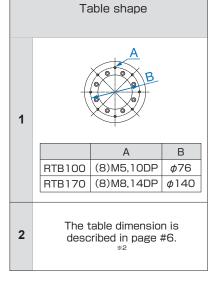
	8		9 1		10
	Mountin	g cla	amps	N	lotor
	Guide blocks	Clamp block			
1	1 For 14mm T-groove		For 14mm T-groove	W	Supplied by Sankyo
2	For 18mm T-groove	2	For 18mm T-groove	Blank	Supplied by customer
0	Not included	0	Not included		

10

•	•		
Set of guide blocks	A complete set of hardwares		
		RTB100	RTB170
2 guide blocks	Hardwares	4 pcs.	4 pcs.
2 Allen-head bolts (M6)	T- slot nuts(M12)	4 pcs.	6 pcs.
	Hexagon bolt(M12)	4 pcs.	4 pcs.
	Washers(M12)	4 pcs.	4 pcs.
	Hexagon socket head bolt (M12)	_	4 pcs.

	Connector position					
	Tilting axis	Support axis				
S		S				
В		В				
F						





X

11 Standard/ Custom

Standard

Custom

Blank

Χ

^{**1} Please contact us for details about external controller specifications.
**2 RTB100 is not available with a T-groove table.

Specification

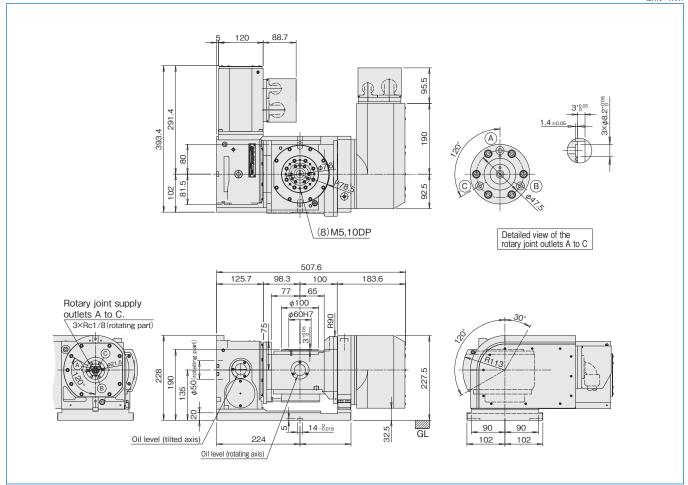
Specifications			RTB100		RTB	170	
Specifications			Rotary axis	Tilt axis	Rotary axis	Tilt axis	
Tilting angle		deg	−30 to +120		-30 to +120		
Table diameter		mm	φ100		φ1	70	
Table pilot bore diamete	r	mm	φ60	O +0.03	φ6	O +0.03	
Center height at tilted a	xis +90°	mm	10	35	18	85	
Tabletop height at 0° tilt	ed axis	mm	15	90	20	265	
Guide block width		mm	14	-0.018	14	-0.018	
Gear ratio		_	1/40	1/50	1/50	1/60	
Inertia at motor shaft *1	*2	×10 ⁻⁴ kg⋅m ²	2.20	1.30	2.96	5.11	
Motor model(FANUC)		-	αiS2/5000 (A06B-2212-B400)	αiS2/5000 (A06B-2212-B400)	αiS4/5000 (A06B-2215-B400)	αiF8/3000 (A06B-2227-B400	
Maximum table speed		min ⁻¹	100	100	70	50	
Indexing accuracy		arc.sec	±15	±30	±15	±30	
Repeatability		arc.sec	8	8	8	8	
Net weight		kg	90		180		
Allow When horizontal		kg	35		110		
Allowable payload When tilted	w	kg	20		70		
Allowable workpiece inertia		kg·m²	0.09		0.65		
Maximum eccentric load torque WXL		N∙m	59		246		
ĮF.		N	7800		9000		
Hota	Continuous holding torque *2.*3 Maximum output torque *2.*3	N∙m	98		236		
Allowable load		N∙m	177		362		
₽ F = F	Continuous	N∙m	12	22	5	12	
F×L ax	. Maximum output torque *2,*3	N∙m	22	21	98	87	
Built-in rotary joint(numb	- Catpat torque		3			 6	
, , , , , , , , , , , , , , , , , , , ,	built-in rotary joint(flumber of ports)			<u> </u>		-	

 $[\]ensuremath{\ast}\ensuremath{\mbox{1}}$. The specified motor shaft equivalent inertia does not include the inertia of the motor shaft.

^{*2.} The converted motor shaft inertia, and the continuous and maximum holding torque are the values when using a FANUC motor. Please contact us if you want to use other motors.

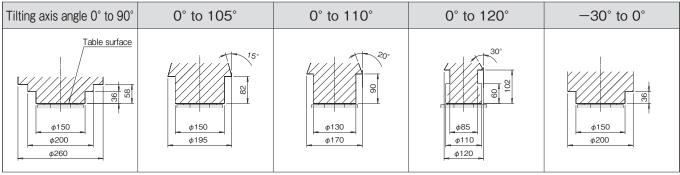
^{*3.}Maximum holding torque shall be a maximum of 10 seconds at a 20% duty cycle.

RTB100-AFSF1-J



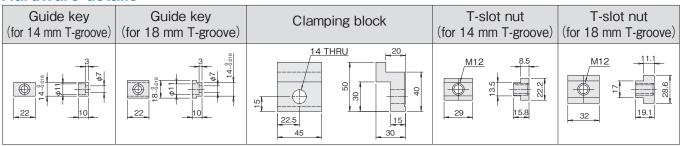
- *The above dimensions are for a machine equipped with a FANUC motor.
- *Specifications and dimensions are subject to change without notice, so please check again when ordering.

Area for mounting workpieces

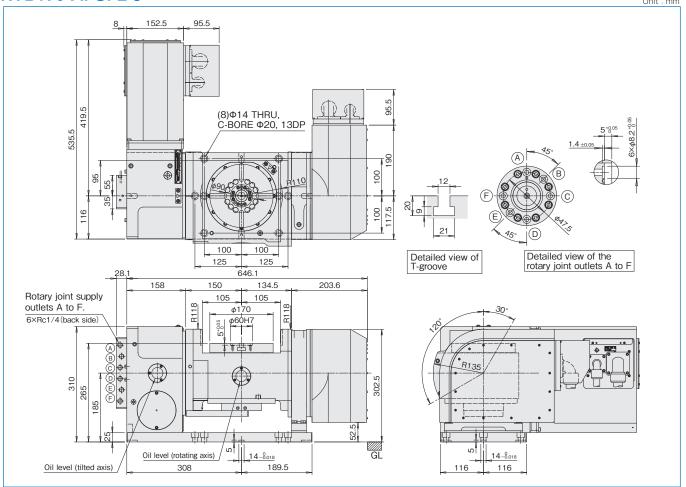


[•] Set parameter to avoid interference.

Hardware details

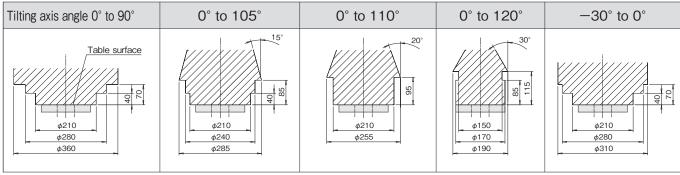


RTB170-AFSF2-J



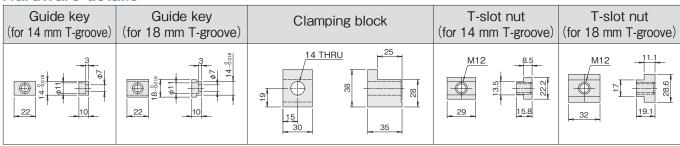
- *The above dimensions are for a machine equipped with a FANUC motor.
- *Specifications and dimensions are subject to change without notice, so please check again when ordering.

Area for mounting workpieces



[•] Set parameter to avoid interference.

Hardware details



Compatible Servomotor Models

With brake

Model		FANUC	MITSUBISHI	SANYO (Brother type)
RTB100	Rotary axis	lphaiS2/5000 (A06B-2212-B400)	-	R2AA08075FCRGYM6
KIBIOO	Tilt axis	αiS2/5000 (A06B-2212-B400)	_	R2AA08075FCRGYM6
RTB170	Rotary axis	αiS4/5000 (A06B-2215-B400)	HG105BS-S105010	R2AAB8100FCRGYM
KIBITO	Tilt axis	αiF8/3000 (A06B-2227-B400)	HG104BS	R2AAB8100FCRGYM

Without brake

Model		FANUC	MITSUBISHI	SANYO (Brother type)
RTB100	Rotary axis	lphaiS2/5000 (A06B-2212-B100)	-	-
KIBIOO	Tilt axis	αiS2/5000 (A06B-2212-B100)	-	-
RTB170	Rotary axis	αiS4/5000 (A06B-2215-B100)	HG105S-S105010	_
KIBI70	Tilt axis	αiF8/3000 (A06B-2227-B100)	HG104S	-

^{*1.} If a motor brake control is not possible, select the code for a servo motor that doesn't have a brake.

However, please note that this mechanism does not self-lock, so the table may rotate depending on its posture in the event of a power failure.

Precision Rating

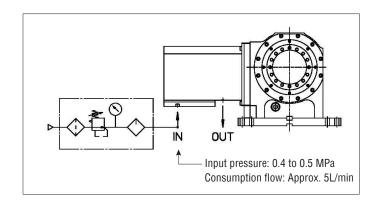
No.	Measurement		Method	RTB100	RTB170
1	Straightness of table top			0.015mm over full length	0.015mm over full length
2	Parallelism between table top and bottom surface of base			0.015mm	0.015mm
3	Runout of table top		-0-1	0.01mm	0.01mm
4	Runout of table pilot bore			0.01mm	0.01mm
5	Parallelism between tilt axis center line and bottom surface of base			0.02mm over full length	0.02mm over full length
6	Parallelism between table top and guide block			0.02mm	0.02mm
7	Indexing accuracy	Rotary axis		±15arc.sec	±15arc.sec
,	indexing accordes	Tilt axis		±30arc.sec	±30arc.sec
8	Repeatability	Rotary axis		8arc.sec	8arc.sec
	1 lopoutubility	Tilt axis		8arc.sec	8arc.sec

Precautions

Air supply

Sankyo's CNC rotary tables come standard equipped with an air purge outlet. (Use it to blow out condensation and coolant to prolong the life of electrical parts and prevent rust in the motor housing.) Supply clean air for the air purge by referring to the drawing shown.

(Do NOT block the exhaust outlet.)



Lubrication

Sankyo's CNC rotary tables use high-performance lubrication oil. Although the lubricant is chemically and thermally stable, it should be changed every 3,000 hours of operation in order to ensure longer product life. Even if operated less than 3,000 hours, the oil should be changed once per year. The condition of the oil can be checked with the oil level gauge while the unit is in the stop condition. Check the oil level and color. If the level is low or the color has changed, change the oil regardless of the number of operation hours. Some air bubbles may form in the oil during operation. This is normal and does not affect quality.

* Be sure to use only the lubricant specified below. Otherwise service life may be reduced and parts may deteriorate. Specified lubricant: Mobil SHC629 (VG150)

Use in grinding machines

When used in grinding machines, the seal device on the outer periphery of the table may become damaged. The warranty does not cover such damage.

Maximum rotation speed

The maximum rotation speed for the table given in the specifications refers to the indexing speed. Consult with Sankyo if the table is to be rotated continuously. Otherwise, the table will heat up and lose accuracy, causing overload alarms with the servo motor.

Rotary joint

Use hoses for plumbing in the stationary sections. If oil film leaks from the pneumatic circuit, it will cause a serious problem. Install a bleed circuit between the two circuits. Avoid continuous rotation as it may cause heat buildup in the internal seals. The gasket port mounting surface (O-ring seal surface) should be a flat with a surface roughness not higher than Rz 6.3. The fluid used and the pressure must be within the following range.

Each RJ port: Hydraulic pressure; up to 6.0 MPa, pneumatic pressure; up to 0.7 MPa

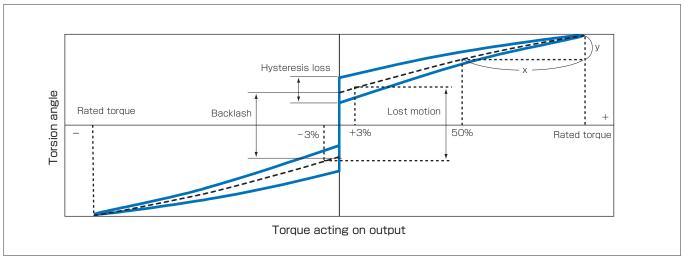
General Precautions

- Under the Japanese trade regulation, RollerDrive CNC can be restricted to supply or export to a country which may produce weapons or related products.
- Dimensions and specifications are subjected to be modified without notice.
- Contents of this catalogue is published in October 2023.
- Whole or part of the contents, mechanisms, logos, drawings belongs to Sankyo-Seisakusho, Japan. No part of the catalogue is allowed to copy or redistributed to the third party without the permission of Sankyo Seisakusho.

Technical information

Backlash, lost motion, hysteresis loss

General hysteresis graph



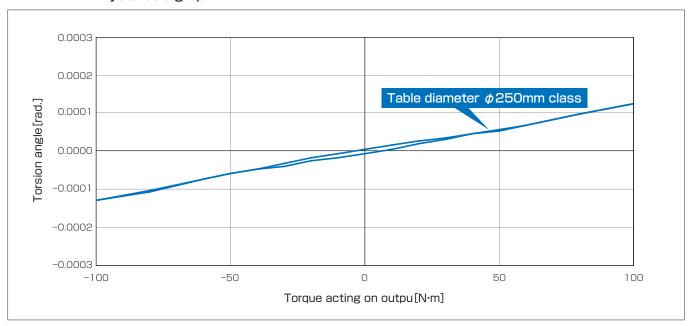
** BacklashLost motionHysteresis loss

Rotation angle which can arise even with zero torque (looseness)

Torsion angle of the midpoint of the hysteresis curve width which arises when applying $\pm 3\%$ rated torque

Torsion angle where there is no complete return, when torque is applied in both forward and reverse directions

RollerDrive® hysteresis graph

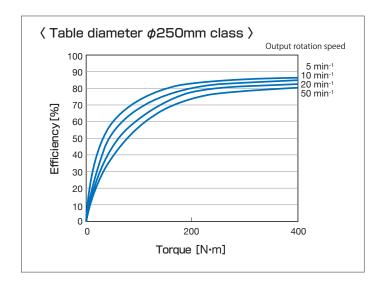


For a general positioner, the hysteresis graph can be obtained by applying torque to the output shaft, and plotting the generated torsion angle. Backlash, lost motion and hysteresis loss can each be defined from the hysteresis graph, as indicated above. Lost motion and hysteresis loss depend on the material characteristics, and occur in all types of structures. Backlash, on the other hand, occurs only when there are gaps or looseness in the structure. Backlash has a major effect on accuracy, servo gain and similar factors, and must be minimized. With *RollerDrive*°, backlash is completely eliminated using our unique preload structure, and lost motion and hysteresis loss are controlled to extremely small values due to the results of research on optimizing materials and structures.

Efficiency

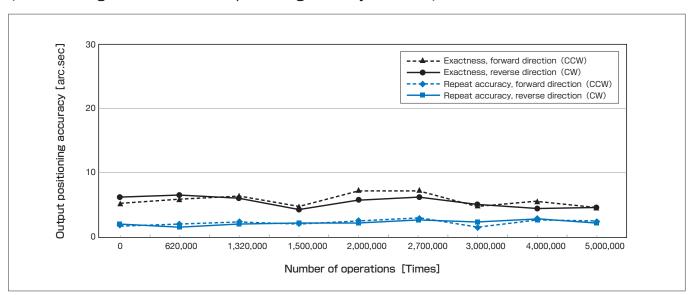
This indicates the percent of input power which is transmitted to the output.

The **RollerDrive**° motion mechanism has high efficiency because it employs rolling contact. Efficiency varies depending on conditions such as load torque, rotation speed and temperature.



Durability

⟨ Test of changes in *RollerDrive*® positioning accuracy over time ⟩

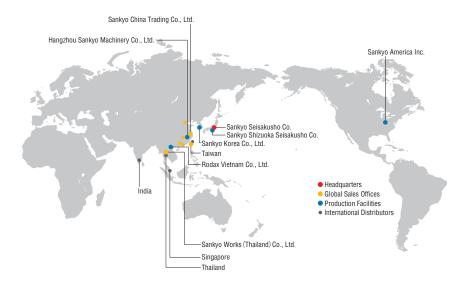


Test conditions		
RollerDrive size	RA125 class test machine	
Output load weight	152 kg(\$\phi\$500mm)	
Output load moment of inertia	4.69kg·m ^²	
Output rotation angle	0-345degree(Reciprocating	
Output maximum rotation speed	100min ⁻¹	
Acceleration time	0.100sec	
Uniform speed time	0.475sec	
Deceleration time	0.100sec	

In the *RollerDrive**, all rotating elements operate in a state of rolling contact, and thus there is almost no wear, or degradation in accuracy over time.

There is almost no change in positioning accuracy after testing operation 5 million times, and this shows that the outstanding accuracy of the *RollerDrive*°can be maintained over the long term.

Global network



Group Companies

Sankyo America Inc. 10655 State Route 47 Sidney, Ohio, 45365 U.S.A. Phone: +1-(10)837-498-4901 Fax: +1-(0)937-498-9403 Email: sales@sankyoautomation.com

Sankyo Korea Co., Ltd. 1449-48 Seobu-ro, Gwonseon-gu, Suwon-si, Gyeonggi-do, 16643 Korea Phone: +82-(0)31-895-5991 Fax: +82-(0)31-895-6607 Email: kr-sales@rollerdrive.com

Sankyo China Trading Co., Ltd. [Shanghai Sales Office] Room101, Unit 2, No. 159 Tianzhou Road, Shanghai 200233, China Phone: +86-(0)21-5445-2813 Fax: +86-(0)21-5445-2340 Email: sales@sankyochina-trading.com

[Shenzhen Sales Office] Unit 19j, Tower B, Neo Building, No.6009 Shennan Avenue, Futian District, Shenzhen China Phone: +86-(0)755-8230-0270 Fax: +86-(0)755-8236-4605

[Tianjin Sales Office]
Room 1905, Pengzhanfeiwo Building A, Crossing Yale Road Yaolin Road,
Xiqing District, Tianjin 300380 China
Phone: +86-(0)22-2312-1005 Fax: +86-(0)22-2312-1007

[Guangzhou Sales Office] Room 913, Xing Pu Buliding, No.12 Guan Hong Road, Guangzhou Economic Development Zone, Huang Pu, Guang Zhou 510670 China Phone: +86-(0)20-8985-1846 Fax: +86-(0)20-8225-7346

[Wuhan Sales Office] Room 2301, Taihe Square, No.134 Wusheng Road, Wuhan, Hubei Province China Phone: +86-(0)27-8568-5818 Fax: +86-(0)27-8568-2818

Hangzhou Sankyo Machinery Co., Ltd. No.2518 Jiang Dong 2 Road, Hangzhou Jiang Dong Industrial Park, Xiaoshan Zone, Hangzhou, Zhejiang, China Phone: +86-(0)571-8283-3311 Fax: +86-(0)571-8283-1133

Rodax Vietnam Co., Ltd. Plot No. M1, Thang Long Industrial Park Ii Di Su, My Hao, Hung Yen, Viet Nam Phone: +84-(0)221-3-589701 Fax: +84-(0)221-3-589708

Sankyo Works (Thailand) Co., Ltd. 9/31 Moo 5, Phaholyotin Road, Klongnueng, Klong Luang, Patumthani 12120 Thailand Phone: +66-(0)2-516-5355 Fax: +66-(0)2-068-0931 Email: sales@sankyo-works.co.th

Contact us

Mon-Fri AM8:30-12:00 PM13:00-17:30 UTC + 09:00 (JST) (Except public holidays and company holidays)

3-37-3 Tabatashinmachi, Kita-ku, Tokyo, Japan 114-8538 Phone: +81-(0)3-3800-3305 Headquarters (International Sales Division)

Fax: +81-(0)3-3800-3378

Email: overseas@sankyo-seisakusho.co.jp URL: https://www.sankyo-seisakusho.co.jp

■ Taiwan Sales Office No.21, Ln.152, Jianxing Rd., Sanhe Vil., Daya Dist., Taichung City 42876, Taiwan (R.O.C.)

Phone: +886-(0)4-2359-4048 Fax: +886-(0)4-2359-4720 Email: tw-sales@rollerdrive.com



https://www.sankyo-seisakusho.co.jp

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